

RIEGL VQ[®]-380i

- **high ranging based on echo digitization and online waveform processing**
- **high laser repetition rate - fast data acquisition**
- **multiple target capability**
- **interface for smooth integration of GPS**
- **perfectly linear scan lines**
- **compact, rugged, and lightweight design**
- **integrated LAN-TCP/IP interface**

The V-Line[®] 2D Laser Scanner **RIEGL VQ-380i** provides high speed data acquisition using a narrow infrared laser beam and a fast line scanning mechanism.

High-accuracy laser ranging is based on **RIEGL's** unique echo digitization and online waveform processing, which allows achieving superior measurement capability even under adverse atmospheric conditions and the evaluation of multiple target echoes.

The scanning mechanism is based on a fast rotating multi-facet polygonal mirror, which provides fully linear, unidirectional and parallel scan lines.

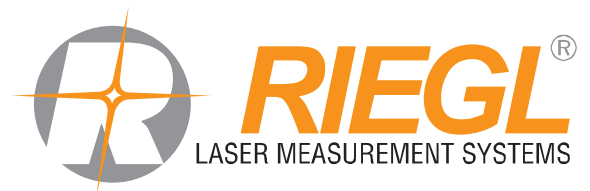
The **RIEGL VQ-380i** is a very compact and lightweight device, mountable in any orientation and also under limited space conditions on small fixed-wing aircrafts, helicopters and land based vehicles. The instrument needs only one power supply and provides line scan data via the integrated LAN-TCP/IP interface. The binary data stream can easily be decoded by user-designed software making use of the available software library RiVLib.

Typical applications include

- **Terrain Mapping**
- **Corridor Mapping**



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www.riegl.com



Laser Product Classification

Class 1 Laser Product according to IEC60825-1:2007

The following clause applies for instruments delivered into the United States:
Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007.



Range Measurement Performance

Measuring Principle

time of flight measurement, echo signal digitization,
online waveform processing, multiple-time-around-processing

Laser Pulse Repetition Rate PRR ¹⁾	70 kHz	100 kHz	200 kHz	300 kHz	400 kHz	550 kHz
Effective Measurement Rate (meas./sec.) ¹⁾²⁾	29 000	42 000	83 000	125 000	167 000	230 000
Max. Measuring Range ³⁾⁴⁾						
natural targets $\rho \geq 20\%$	850 m	700 m	500 m	450 m	350 m	300 m
natural targets $\rho \geq 60\%$	1400 m	1200 m	850 m	700 m	650 m	550 m
Max. Operating Flight Altitude AGL ¹⁾²⁾	475 m (1550 ft)	400 m (1300 ft)	275 m (900 ft)	250 m (820 ft)	200 m (650 ft)	175 m (570 ft)
Max. Number of Targets per Pulse	practically unlimited (details on request)					

1) Rounded values.
2) Reflectivity $\rho \geq 20\%$, 100° FOV, additional roll angle $\pm 5^\circ$.
3) Typical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. In bright sunlight, the max. range is shorter than under overcast sky.
4) Ambiguity to be resolved by post-processing with RIMTA ALS software.

Minimum Range

10 m

Accuracy⁵⁾⁷⁾

25 mm

Precision⁶⁾⁷⁾

25 mm

Laser Pulse Repetition Rate¹⁾⁸⁾

up to 550 kHz

Max. Effective Measurement Rate¹⁾

up to 230 000 meas./sec. (@ 550 kHz PRR & 100° FOV)

Echo Signal Intensity

for each echo signal, high-resolution 16 bit intensity information is provided

Laser Wavelength

near infrared

Laser Beam Divergence⁹⁾

0.35 mrad

Laser Beam Footprint (Gaussian Beam Definition)

36 mm @ 100 m, 88 mm @ 250 m, 175 mm @ 500 m

5) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.
6) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.

7) One sigma @ 150 m range under *RIEGL* test conditions.
8) User selectable.
9) Measured at the $1/e^2$ points. 0.35 mrad corresponds to an increase of 35 mm of beam diameter per 100 m distance.

Scanner Performance

Scanning Mechanism

rotating polygon mirror

Field of View (selectable)

100° (+60° / -40°)

Scan Speed (selectable)

10 - 120 scans/sec

Angular Step Width $\Delta \vartheta$ (selectable)

$0.004^\circ \leq \Delta \vartheta \leq 0.41^\circ$

between consecutive laser shots

Angle Measurement Resolution

0.001°

Internal Sync Timer

for real-time synchronized time stamping of scan data

Scan Sync (optional)

scanner rotation synchronization

Data Interfaces

Configuration

LAN 10/100/1000 Mbit/sec

Scan Data Output

LAN 10/100/1000 Mbit/sec, USB 2.0

GPS-System

Serial RS232 interface for data string with GPS-time information,
TTL input for 1PPS synchronization pulse

Mechanical Interfaces

Mounting of the Laser Scanner

3 x M6 thread inserts in the rear and the front plate
removable mounting plate with 6 x M6 thread inserts

Mounting of IMU sensor

3 x M6 thread inserts in the rear plate
(rigidly coupled with the internal mechanical structure)

General Technical Data

Power Supply Input Voltage

18 - 32 V DC

Current Consumption

typ. 72 W

Main Dimensions / Weight

294.5 x 198 x 185 mm (L x W x H), approx. 7.10 kg

Humidity

max. 80 % non condensing @ +31°C

Protection Class

IP64, dust and splash-proof

Max. Flight Altitude (operating)

16 500 ft (5 000 m) above MSL

Max. Flight Altitude (not operating)

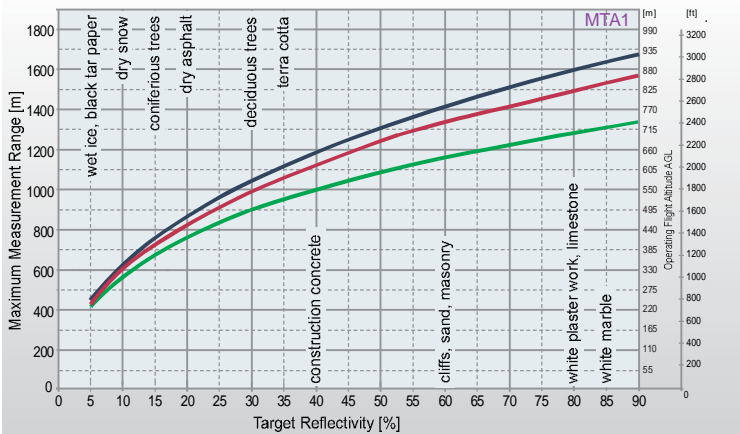
18 000 ft (5 500 m) above MSL

Temperature Range

-10°C up to +40°C (operation) / -20°C up to +50°C (storage)

Maximum Measurement Range & Point Density RIEGL VQ[®]-380i

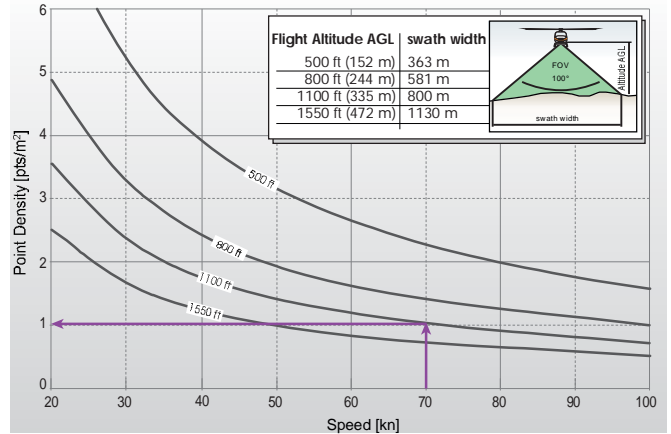
PRR = 70 kHz



MTA1: no ambiguity / 1 transmitted pulse „in the air“

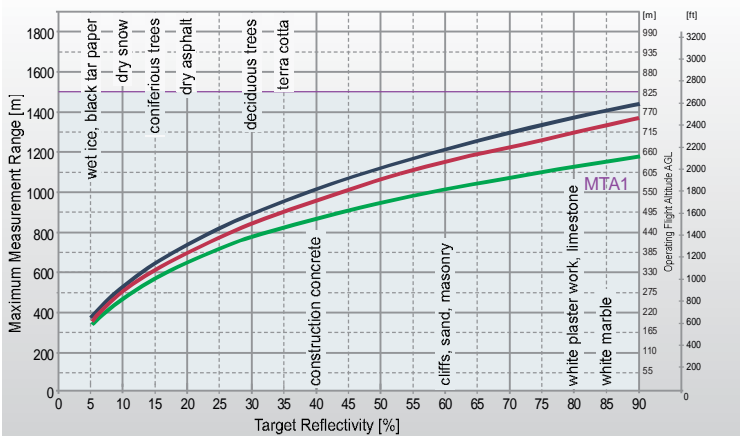
— @ visibility 23 km
— @ visibility 15 km
— @ visibility 8 km

PRR = 70 kHz



Example: VQ-380i at 70,000 pulses/second
Altitude = 1100 ft AGL, Speed = 70 kn
Resulting Point Density ~ 1 pt/m²

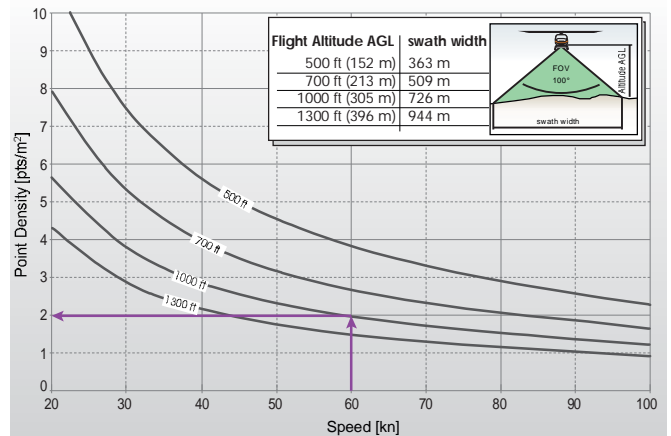
PRR = 100 kHz



MTA1: no ambiguity / 1 transmitted pulse „in the air“

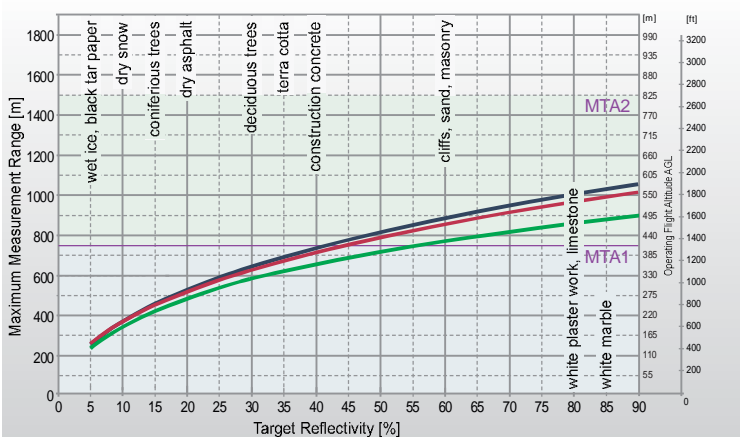
— @ visibility 23 km
— @ visibility 15 km
— @ visibility 8 km

PRR = 100 kHz



Example: VQ-380i at 100,000 pulses/second
Altitude = 1000 ft AGL, Speed = 60 kn
Resulting Point Density ~ 2 pt/m²

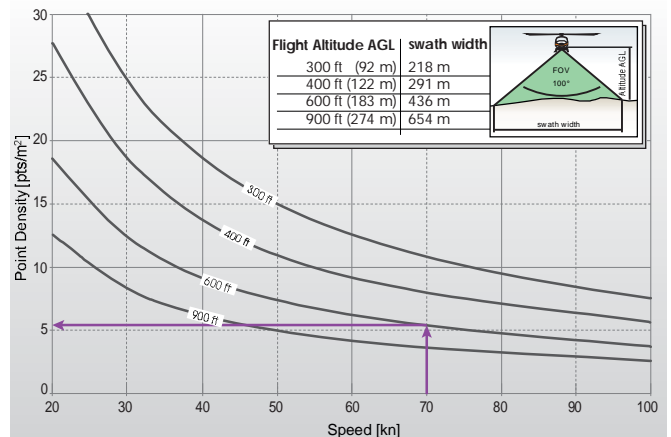
PRR = 200 kHz



MTA1: no ambiguity / 1 transmitted pulse „in the air“

— @ visibility 23 km
— @ visibility 15 km
— @ visibility 8 km

PRR = 200 kHz



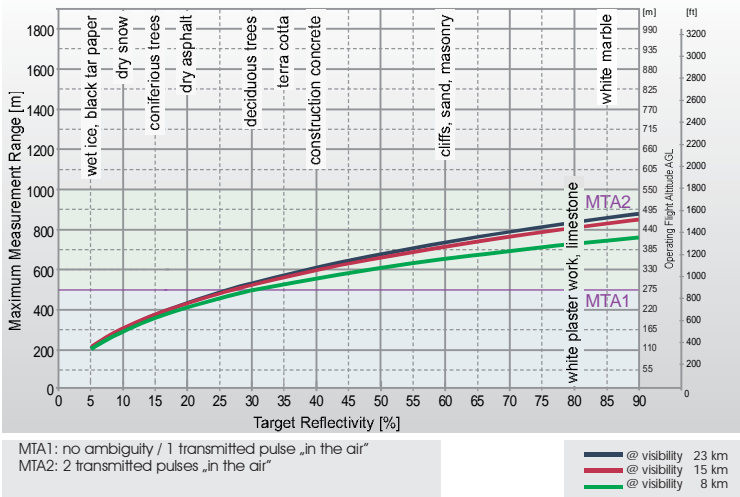
Example: VQ-380i at 200,000 pulses/second
Altitude = 600 ft AGL, Speed = 70 kn
Resulting Point Density ~ 5 pt/m²

The following conditions are assumed for the Operating Flight Altitude AGL

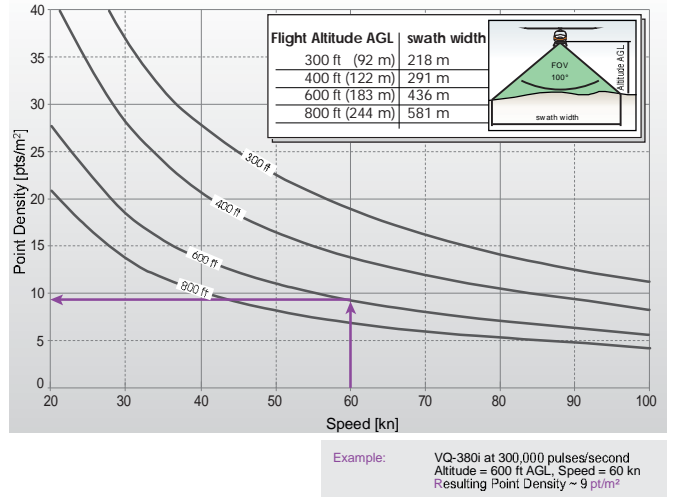
- ambiguity resolved by multiple-time-around (MTA) processing & flight planning
- target size ≥ laser footprint
- scan angle 100°
- average ambient brightness
- roll angle +/-5°

Maximum Measurement Range & Point Density RIEGL VQ®-380i

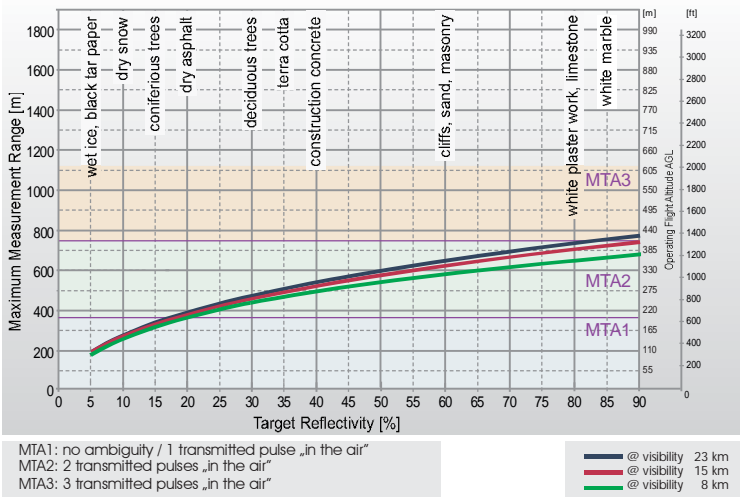
PRR = 300 kHz



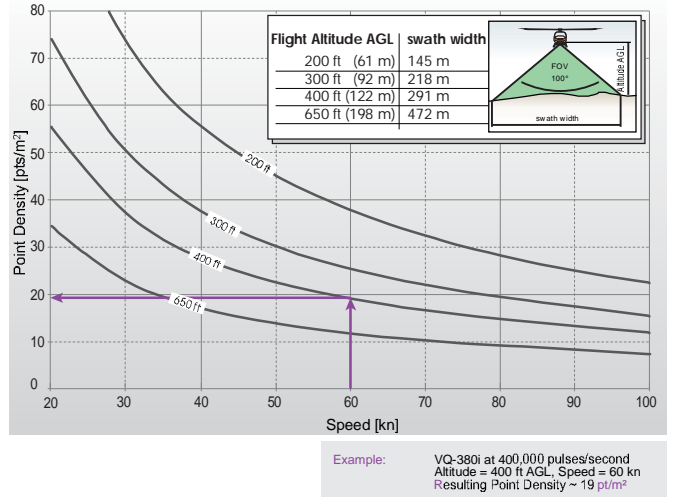
PRR = 300 kHz



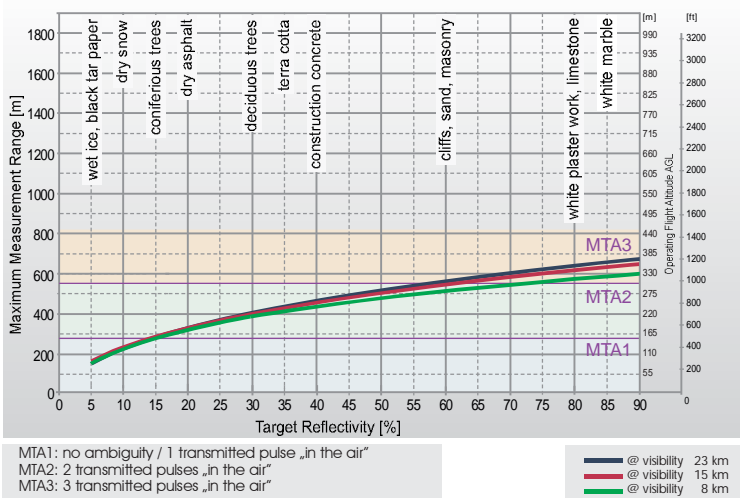
PRR = 400 kHz



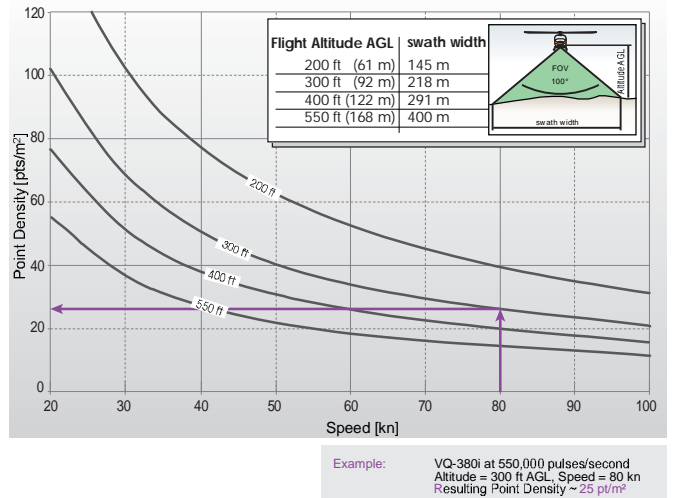
PRR = 400 kHz



PRR = 550 kHz



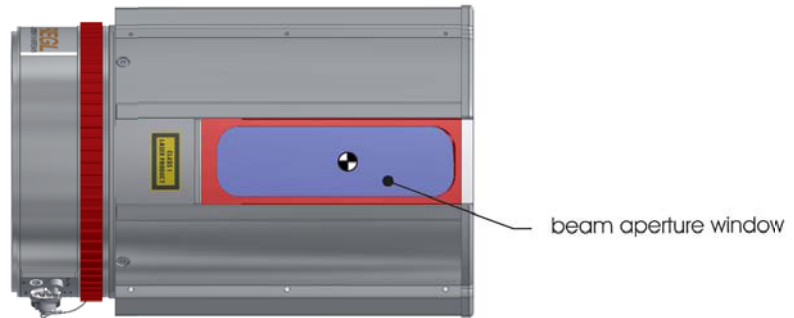
PRR = 550 kHz



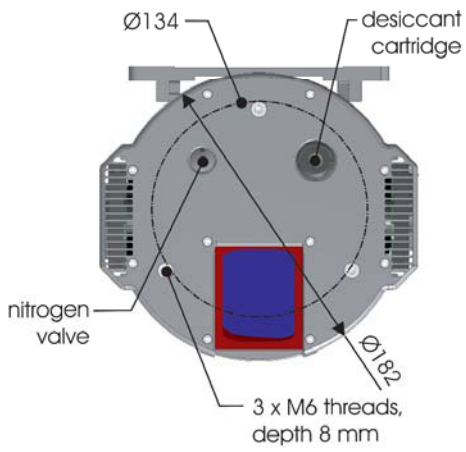
The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing & flight planning
- target size \geq laser footprint
- scan angle 100°
- average ambient brightness
- roll angle +/- 5°

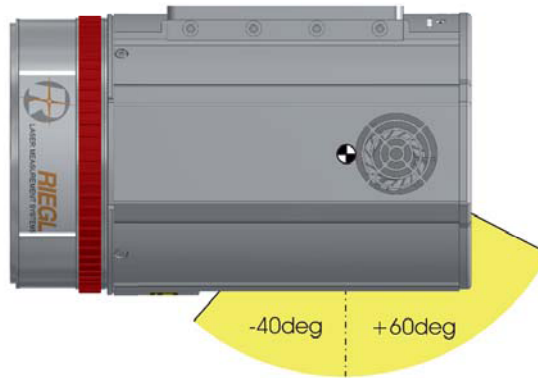
bottom view



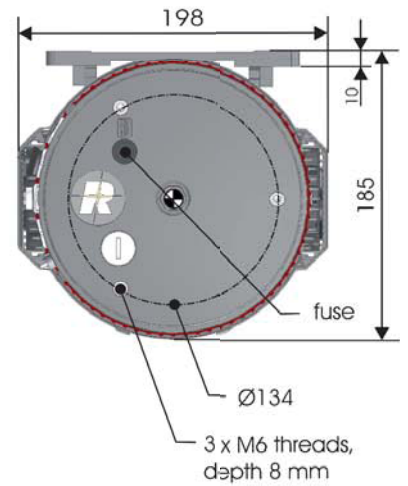
front view



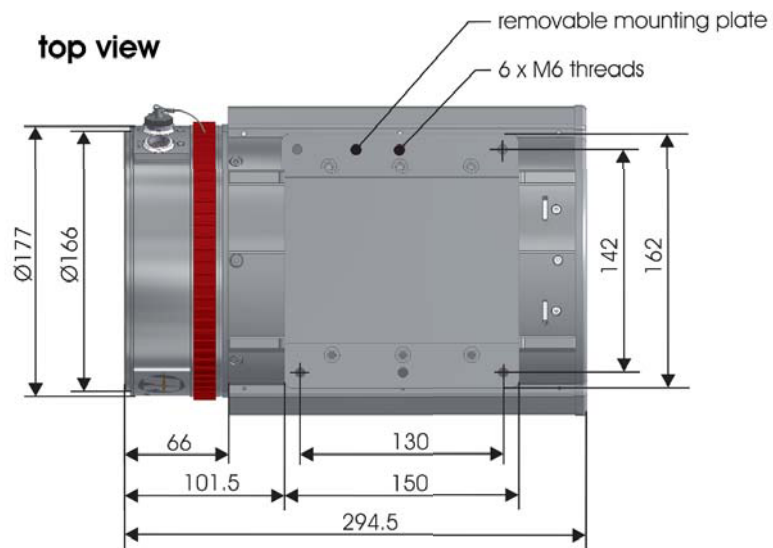
side view



rear view



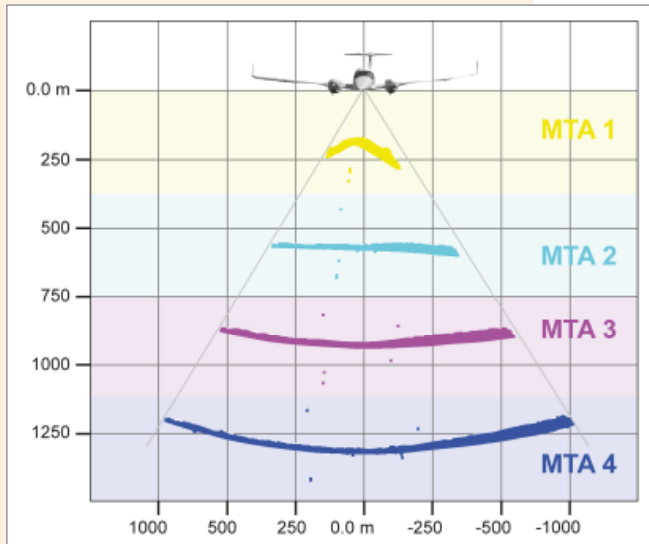
top view



all dimensions in mm

⊙ origin of scanner's local coordinate system

Multiple-time-around Data Acquisition and Processing



Example for a profile of scan data processed in MTA zones 1 to 4

In time-of-flight laser ranging a maximum unambiguous measurement range exists, which is defined by the laser pulse repetition rate and the speed of light. In case the echo signal of an emitted laser pulse arrives later than the emission of the subsequently emitted laser pulse, the range result becomes ambiguous – an effect known as „Multiple-Time-Around“ (MTA).

The *RIEGL VQ-380i* allows ranging beyond the maximum unambiguous measurement range using a sophisticated modulation scheme applied to the train of emitted laser pulses. The dedicated post-processing software *RiMTA ALS* provides algorithms for multiple-time-around processing, which automatically assign definite range results to the correct MTA zones without any further user interaction required.



Edificio Antalia
Albasanz, 16
28037 MADRID
Tel. 91 567 97 00
Fax: 91 570 26 61
www.alvaingenieros.com



Torre Mapfre-Vila Olímpica
Marina, 16 - Planta 11-C2
08005 BARCELONA
Tel. 93 459 42 50
Fax: 93 459 42 62
alava@alava-ing.es

www.riegl.com